

Based on joint works with

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Euler's equation

$$\begin{cases}
\exists_{u} + u \cdot \nabla u + \nabla p = 0 \\
div u = 0
\end{cases}$$
models an idealized/inviscid fluid.

$$u : [0, T] \times IR^{d} \longrightarrow IR^{d} \quad velocity$$

$$p : [0, T] \times IR^{d} \longrightarrow R \quad pressure$$
Given u, consider Lagrangian trajectories

$$f_{t} = u_{t}(\varphi_{t})$$

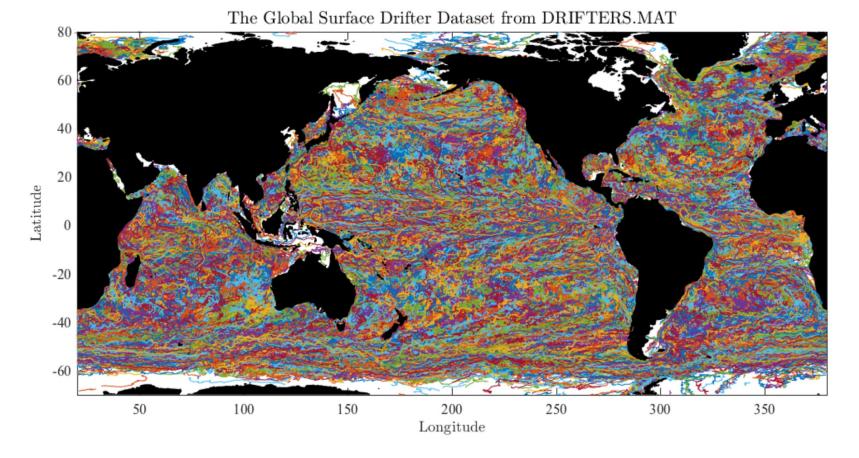


FIGURE 1.1. This figure shows latitude and longitude of Lagrangian trajectories of drifters on the ocean surface driven by the wind and ocean currents, as compiled from satellite observations by the National Oceanic and Atmospheric Administration Global Drifter Program. Each colour corresponds to a different drifter, see [33]. Upon looking carefully at the individual Lagrangian paths in this figure, one sees that each of them evolves as a mean drift flow, composed with an erratic flow comprising rapid fluctuations around the mean.



f. = "mean drift" + "erratic flow" = $u_{\ell}(\phi_{\ell}) + vandom term$ = $U_{t}(\phi_{t}) + 3_{x}(\phi_{t})W_{t}$ · (W+) imagular/noisy term · (3') K fixed, used to fit made (to data. - + What is the corresponding PDE?

Can use solve the equation?
Consider
$$d=2$$
 and look at the vorticity
 $w = curlu = \nabla x u = \partial_{1}u^{2} - \partial_{2}u^{1}$
Satisfies
 $\partial_{4}w + u \cdot \nabla w + 3_{K} \cdot \nabla w \dot{W}^{K} = 0$
The velocity can be recovered via Biot - Savart
 $u_{4}(X) = K_{M}w_{4}(X) = \int K(X-Y)w_{4}(Y)dY$, $K(z) = \frac{z^{L}}{2K|z|^{2}}$

Hethod of characteristics:

$$\frac{d}{dt} \omega_{t}(\varphi_{t}) = \Im_{u}(\varphi_{t}) + D\omega_{t}(\varphi_{t}) \dot{\varphi}_{t}$$

$$= (\Im_{t}\omega_{t} + u_{t} \cdot \nabla \omega_{t} + 3_{t} \cdot \nabla \omega_{t} \dot{W}_{t}^{k})(\varphi_{t}) = 0$$
since $\dot{\varphi}_{t} = \omega_{t}(\varphi_{t}) + 3_{t}(\varphi_{t})\dot{W}_{t}^{k}$

$$=) \qquad \omega_{t}(\varphi_{t}) = \omega_{0}$$

$$\longrightarrow \qquad \omega_{t} = \omega_{0}(\varphi_{t}^{-1})$$

Leads to the system

$$\begin{cases}
\dot{\phi}_{t} = u_{t}(\phi_{t}) + 3_{k}(\phi_{t}) \dot{w}_{k}^{k} \\
\dot{\psi}_{t} = K \cdot \omega_{t} \\
\dot{\omega}_{t} = \omega_{o}(\phi_{t}^{-})
\end{cases}$$

Yudovich theory; well-posedness in the
class
$$W \in L^{\infty}([0,T]; L^{n}L^{\infty}(\mathbb{R}^{2}))$$

Rough paths Rough diff. eq.
First
$$u = 0$$
, eq reads
 $\dot{\phi}_{\epsilon} = 3u(\phi_{\epsilon}) \dot{W}_{\epsilon}^{\nu}$
Integrate
 $\phi_{\epsilon} - \phi_{s} = \int_{s}^{t} 3u(\phi_{r}) \dot{W}_{r}^{\nu} dr = \int_{s}^{t} 3u(\phi_{r}) dW_{r}^{\nu}$
When is integration well defined?

The Lyoung, 1936]
If

$$1g_{\epsilon} - g_{s} | \leq |t \cdot s|^{\kappa}$$
, $1h_{\epsilon} - h_{s} | \leq |t \cdot s|^{3}$
and $\kappa + B > 1$
then $\int_{S} g_{r} dh_{r} = \lim_{|t| \to 0} \sum_{t} g_{\epsilon} (h_{\epsilon} - h_{\epsilon})$
is well defined and
 $1\int_{s}^{\xi} g_{r} dh_{r} - g_{\epsilon} (h_{\epsilon} - h_{s}) | \leq |t - s|^{\kappa + B}$.

If W is x-Hölder and
$$3_{\mu}(\phi_{\cdot})$$
 is B-Hölder;
 $\phi_{\xi} \cdot \phi_{s} = \int_{3}^{\xi} 3_{\mu}(\phi_{\cdot}) dW_{\tau}^{\mu} \mp 3_{\mu}(\phi_{\cdot}) (W_{\xi}^{\mu} - W_{s}^{\mu})$
 $\downarrow \quad |\xi \cdot s|^{\alpha + \beta} + ||3_{\mu}||_{0} \quad |\xi \cdot s|^{\alpha}$
Expect ϕ to inherit
regularity of W, so $\alpha = \beta$.
Need $\alpha + \kappa > (-7) \quad \kappa > \frac{1}{2}$

For sample paths of Brownian motion
have
$$x = \frac{1}{2} - \frac{2}{5}$$
 for $\varepsilon > 0$, so Young theory
is out of reach.
In fact

Proposition 1.1. There exists no separable Banach space $\mathcal{B} \subset \mathcal{C}([0,1])$ with the following properties:

- 1. Sample paths of Brownian motions lie in B almost surely.
- 2. The map $(f,g) \mapsto \int_0^{\cdot} f(t)\dot{g}(t) dt$ defined on smooth functions extends to a continuous map from $\mathcal{B} \times \mathcal{B}$ into the space of continuous functions on [0,1].

[I. Lyons, 91]

But;
$$\int_{0}^{t} B_{r}^{\mu} dB_{r}^{\mu}$$
 can be defined
using It's theory.
However, special care is needed:
 $\sum B_{t,e} \Theta dd_{en} - B_{t}; \longrightarrow \begin{cases} \frac{1}{2}(B_{t}^{2} - t) & \text{if } \Theta = 0\\ \frac{1}{2}B_{t}^{2} & \text{if } \Theta = \frac{1}{2}\end{cases}$
So $B \longmapsto (SB^{\mu} dB_{t})_{\mu,\ell}$ is discontinuous.

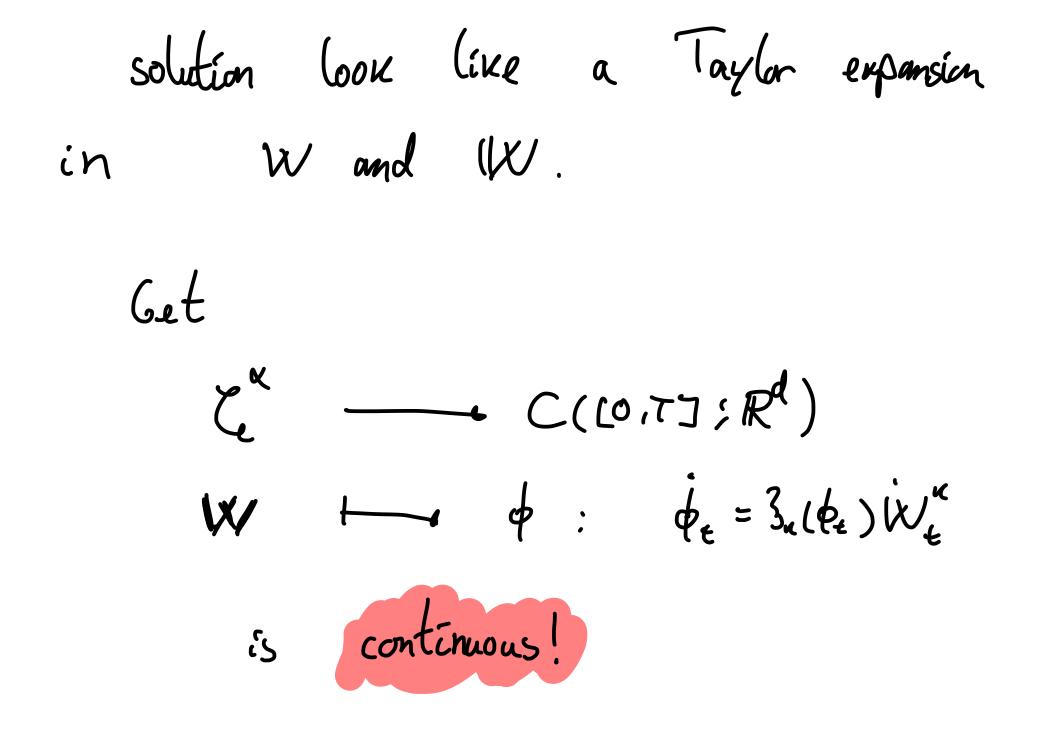
In general, also the solution map is discontinuous $C(0,T]; \mathbb{R}^{k}) \longrightarrow C(0,T); \mathbb{R}^{d})$ $\longmapsto \phi , \phi_t = \mathcal{J}_{\kappa}(\phi_t) \dot{B}_t^{\kappa}$ (B, SBedg) Ēg $\dot{\phi_{t}}' = \ddot{B}_{t}$ $\dot{\phi}_{\pm}^2 = \dot{\phi}_{\pm} \dot{B}_{\perp}^{\prime}$ $\Rightarrow \phi_t^2 = \int B_r^k dB_r^l$



A poir
$$W = (W, W)$$
,
 $W : 10, 73 \longrightarrow \mathbb{R}^{K}$, $W : 10, 73^{2} \longrightarrow \mathbb{R}^{K \times K}$
s.t. $|W_{k} - W_{s}| \leq |t - s|^{\alpha}$, $|W_{se}| \leq |t - s|^{2\alpha}$
and Checks relation
 $W_{st} - |W_{su} - |W_{ut} = (W_{t} - W_{u}) \otimes (W_{u} - W_{s})$
for $x \in (\frac{1}{3}, \frac{1}{2})$ is called a rough path.

Rough differential equations

$$\begin{aligned}
\varphi_{t} - \varphi_{s} &= \int_{3}^{t} (\varphi_{r}) dW_{r}^{\kappa} \\
&= \int_{3}^{t} (\varphi_{s}) + D_{3\kappa}^{2}(\varphi_{s})(\varphi_{r} - \varphi_{s}) + O((\varphi_{r} - \varphi_{s})^{2}) dW_{r} \\
&= 3_{\kappa}(\varphi_{s})(W_{t}^{\kappa} - W_{s}^{\kappa}) + D_{3\kappa}^{2}(\varphi_{s}) \int_{3}^{t} \int_{3}^{t} (\varphi_{u}) dW_{u}^{\ell} dW_{r}^{\kappa} + O((t-s)^{2\kappa}) \\
&= 3_{\kappa}(\varphi_{s})(W_{t}^{\kappa} - W_{s}^{\kappa}) + D_{3\kappa}^{2}(\varphi_{s}) \int_{3}^{t} \int_{3}^{t} dW_{u}^{\ell} dW_{r}^{\kappa} + O((t-s)^{2\kappa}) \\
&= 3_{\kappa}(\varphi_{s})(W_{t}^{\kappa} - W_{s}^{\kappa}) + D_{3\kappa}^{2}(\varphi_{s}) \int_{3}^{t} \int_{3}^{t} dW_{u}^{\ell} dW_{r}^{\kappa} + O((t-s)^{2\kappa}) \\
&= 3_{\kappa}(\varphi_{s})(W_{t}^{\kappa} - W_{s}^{\kappa}) + D_{3\kappa}^{2}(\varphi_{s}) \int_{3}^{t} \int_{3}^{t} dW_{u}^{\ell} dW_{r}^{\kappa} + O((t-s)^{2\kappa}) \\
&= 3_{\kappa}(\varphi_{s})(W_{t}^{\kappa} - W_{s}^{\kappa}) + D_{3\kappa}^{2}(\varphi_{s}) \int_{3}^{t} \int_{3}^{t} dW_{u}^{\ell} dW_{r}^{\kappa} + O((t-s)^{2\kappa}) \\
&= 3_{\kappa}(\varphi_{s})(W_{t}^{\kappa} - W_{s}^{\kappa}) + D_{3\kappa}^{2}(\varphi_{s}) \int_{3}^{t} \int_{3}^{t} dW_{u}^{\ell} dW_{r}^{\kappa} + O((t-s)^{2\kappa}) \\
&= 3_{\kappa}(\varphi_{s})(W_{t}^{\kappa} - W_{s}^{\kappa}) + D_{3\kappa}^{2}(\varphi_{s}) \int_{3}^{t} \int_{3}^{t} dW_{u}^{\ell} dW_{r}^{\kappa} + O((t-s)^{2\kappa}) \\
&= 3_{\kappa}(\varphi_{s})(W_{t}^{\kappa} - W_{s}^{\kappa}) + D_{3\kappa}^{2}(\varphi_{s}) \int_{3}^{t} \int_{3}^{t} dW_{u}^{\ell} dW_{r}^{\kappa} + O((t-s)^{2\kappa}) \\
&= 3_{\kappa}(\varphi_{s})(W_{t}^{\kappa} - W_{s}^{\kappa}) + D_{3\kappa}^{2}(\varphi_{s}) \int_{3}^{t} \int_{3}^{t} dW_{u}^{\ell} dW_{r}^{\kappa} + O((t-s)^{2\kappa}) \\
&= 3_{\kappa}(\varphi_{s})(W_{t}^{\kappa} - W_{s}^{\kappa}) + D_{3\kappa}^{2}(\varphi_{s}) \int_{3}^{t} \int_{3}^{t} dW_{u}^{\ell} dW_{r}^{\kappa} + O((t-s)^{2\kappa}) \\
&= 3_{\kappa}(\varphi_{s})(W_{t}^{\kappa} - W_{s}^{\kappa}) + D_{\delta}^{2}(\varphi_{s}) \int_{3}^{t} \int_{3}^{t} dW_{u}^{\ell} dW_{r}^{\kappa} + O((t-s)^{2\kappa}) \\
&= 3_{\kappa}(\varphi_{s})(W_{t}^{\kappa} - W_{s}^{\kappa}) + D_{\delta}^{2}(\varphi_{s}) \int_{3}^{t} (\varphi_{s}) \int_{3}^{t} (\varphi_{s}) (\varphi_{s}) + D_{\delta}^{2}(\varphi_{s}) \int_{3}^{t} (\varphi_{s}) (\varphi_{s}) (\varphi_{s}) + D_{\delta}^{2}(\varphi_{s}) \int_{3}^{t} (\varphi_{s}) (\varphi_{s}) (\varphi_{s}) + D_{\delta}^{2}(\varphi_{s}) (\varphi_{s}) (\varphi_{s}) (\varphi_{s}) (\varphi_{s}) + D_{\delta}^{2}(\varphi_{s}) (\varphi_{s}) (\varphi_{s})$$



Drifted equation $\phi_t = b_t(\phi_t) + 3_k(\phi_t) W_t$ Zue Varte · 3 « є Съ W = (W, W) arough path • · b has lower regularity (comes from a fluid)

Osgood regular vector field
Say
$$b: [0,T] \times \mathbb{R}^{d} \longrightarrow \mathbb{R}^{d}$$
 is Osgood if
 $|b_{\varepsilon}(x) - b_{\varepsilon}(\overline{x})| \le h(|x-\overline{x}|)$
where $h:\mathbb{R}_{\varepsilon} \longrightarrow \mathbb{R}_{\varepsilon}$ s.t.
 $\int_{0}^{\varepsilon} \frac{1}{h(r)} dr = \infty$
E.g. $h(r) = cr^{k}$ only for $k = 1$
 $h(r) = r(1 - \ln r)$ $(\log - Lipschitz)$

The [Galeati, Leahy, N., 24]
Suppose
$$3_{x} \in C_{2}^{3}$$
, $W \propto$ -rough path, $\kappa \in (\frac{1}{3}, \frac{1}{2})$
and b is bounded and 0 sgood.
Then $\dot{\phi}_{t} = b_{t}(\phi_{t}) + 3_{x}(\phi_{t})\dot{W}_{t}^{\kappa}$, $\phi_{o} = x$
is well-pased and $\phi \in C^{\kappa}(to, \tau]; \mathbb{R}^{d})$
 $\sup_{t \leq \tau} (\phi_{t}, \omega) - \phi_{t}(\overline{z}) | \leq H^{1}(H((w-\overline{z})) + \tau))$
where $H(w) = \begin{cases} \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{cases}$

Thm [Galeati, Leahy, N. 24] • $3_{\kappa} \in C_b$, $div 3_{\kappa} = 0$ · W/ E Ce geometric · b Osgood, dirb = 0 (distributional) then $\phi_{t} = b_{t}(\phi_{t}) + 3u(\phi_{t})\dot{W}_{t}$ is volume preserving $(\phi_t)_{\#} d = d$

Back to fluids
Consider

$$\begin{cases} \dot{\phi}_{\ell} = U_{\ell}(\phi_{\ell}) + 3_{\ell}(\phi_{\ell})\dot{W}_{\ell}^{\mu} \\ U_{\ell} = K_{\star}\omega_{\ell} \\ \omega_{\ell} = W_{0}(\phi_{\ell}^{-1}) \\ \omega_{\ell} = \omega_{0}(\phi_{\ell}^{-1}) \\ where \qquad K(z) = \frac{1}{2\pi} \frac{z^{L}}{|z|^{2}}.$$

Where $K(z) = \frac{1}{2\pi} \frac{z^{L}}{|z|^{2}}.$

when
$$d=2$$
, convolution w/K is smoothing;
sup $|Kxf(x)| \leq ||f||_{L^{1}} + ||f||_{L^{\infty}}$
 $|Kxf(x) - Kxf(\overline{x})| \leq h(|x-\overline{x}|)(||f||_{L^{1}} + ||f||_{L^{\infty}})$
where $h(r) = r(|-(nr)| \leq \frac{r(|-(nr)|)}{r} = \frac{r(|-(nr)|)}{r}$

So given
$$W \in L^{\infty}(U,T]; L' \cap L^{\infty}(\mathbb{R}^{2})$$

$$\dot{\phi}_{t} = u_{t}(\phi_{t}) + 3_{k}(\phi_{t})\dot{w}_{t}^{\prime\prime}$$

Moreover
$$\operatorname{div} K = 0$$
, so
we get a priori estimates
• $\|W_{\ell}\|_{\ell^{1}} = \|W_{0}(\theta_{\ell}^{*})\|_{\ell^{1}} = \|W_{0}\|_{\ell^{1}}$
ound

-
$$\|w_{\ell}\|_{\infty} = \|w_{0}(\dot{\varphi_{\ell}})\|_{\infty} \leq \|w_{0}\|_{\infty}$$

The [Galeali, Leaky, N., 24]
Assume
$$3_{u} \in C_{3}^{2}$$
, div $3_{u} = 0$
and $W' \in T_{u}^{u}$ is geometric. Then
 $\left\langle \dot{p}_{1} = u_{1}(\phi_{1}) + 3_{u}(\phi_{2}) W'_{1}^{u}$
 $u_{u} = K * W_{2}$
 $u_{u} = K * W_{2}$
 $w_{u} = W_{0}(\phi_{u}^{-1})$
is well-posed in the dass
 $W \in L^{\infty}(L^{0}, T); L^{2} \cap L^{\infty}(\mathbb{R}^{2})$

Possible to show well-posedness of

$$u + u \cdot vw + 3u \cdot vw W' = 0$$

 $u = K \cdot wu$
 $w_0 \in L' \wedge L^{\infty}$
from a purely Eulerian perspective.
Uneaser, the solutions can be represented by
Lagrangian trajectories;
LGaleati, Leahy, N. 24]

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