

Connections between L^1 -solutions of Hamilton-Jacobi-Bellman equations and L^∞ -solutions of convection-diffusion equations

Jørgen Endal

URL: <http://folk.ntnu.no/jorgeen>

Department of mathematical sciences//Departamento de Matemáticas
NTNU, Norway//UAM, Spain

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N. Alibaud and E. R. Jakobsen

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- “ L^1 -stability”/Quasicontraction for HJB
- “ L^∞ -stability”/Weighted L^1 -contraction for CDE
- Duality between HJB and CDE



N. ALIBAUD, JE, E. R. JAKOBSEN. **Optimal and dual stability results for L^1 viscosity and L^∞ entropy solutions.** arXiv, 2018.

How are HJB and CDE connected?

$$(HJ) \quad \begin{cases} \partial_t U + H(\partial_x U) = 0 \\ U(\cdot, 0) = U_0 \end{cases} \quad \begin{array}{l} (x, t) \in \mathbb{R} \times (0, \infty) \\ x \in \mathbb{R} \end{array}$$

$$(SCL) \quad \begin{cases} \partial_t u + \partial_x(H(u)) = 0 \\ u(\cdot, 0) = u_0 \end{cases} \quad \begin{array}{l} (x, t) \in \mathbb{R} \times (0, \infty) \\ x \in \mathbb{R} \end{array}$$

If u is the entropy solution of (SCL), then $U := \int^x u$ is the viscosity solution of (HJ) with $U_0 := \int^x u_0$. (Can be made rigorous in 1D.)

So, there is a connection, and in particular, information about u will give information about U .

How are HJB and CDE connected?

We will study the following Cauchy problems in $\mathbb{R}^N \times (0, \infty)$:

$$(HJB) \quad \begin{cases} \partial_t \psi = \sup_{\xi \in \mathcal{E}} \{ b(\xi) \cdot D\psi + \text{tr}(a(\xi)D^2\psi) \} \\ \psi(\cdot, 0) = \psi_0 \end{cases}$$

$$(CDE) \quad \begin{cases} \partial_t u + \text{div}F(u) = \text{div}(A(u)Du) \\ u(\cdot, 0) = u_0 \end{cases}$$

Why? And how are they related?

Note that if $\text{div}(A(u)Du) = \Delta\varphi(u)$, then we replace $\text{tr}(a(\xi)D^2\psi)$ by $a(\xi)\Delta\psi$.

How are HJB and CDE connected?

The Kato inequality for (CDE): For all $0 \leq \phi \in C_c^\infty$ and all $T \geq 0$,

$$\begin{aligned} & \int_{\mathbb{R}^d} |u - v|(x, T) \phi(x, T) \, dx \leq \int_{\mathbb{R}^d} |u_0 - v_0|(x) \phi(x, 0) \, dx \\ \text{(KI)} \quad & + \iint_{\mathbb{R}^d \times (0, T)} \left(|u - v| \partial_t \phi + \sum_{i=1}^d q_i(u, v) \partial_{x_i} \phi \right. \\ & \left. + \sum_{i,j=1}^d r_{ij}(u, v) \partial_{x_i x_j}^2 \phi \right) \, dx \, dt, \\ & q_i(u, v) := \text{sign}(u-v) \int_v^u F'_i(\xi) \, d\xi, \quad r_{ij}(u, v) := \text{sign}(u-v) \int_v^u A_{ij}(\xi) \, d\xi. \end{aligned}$$

How are HJB and CDE connected?

For a.e. $x \in \mathbb{R}^N$ and $t \geq 0$:

$$I := \sum_{i=1}^d q_i(u, v) \partial_{x_i} \phi + \sum_{i,j=1}^d r_{ij}(u, v) \partial_{x_i x_j}^2 \phi = q(u, v) \cdot D\phi + \text{tr}(r(u, v) D^2 \phi)$$

$$\begin{aligned} I &= \text{sign}(u(x, t) - v(x, t)) \times \\ &\quad \times \int_{v(x, t)}^{u(x, t)} \{ F'(\xi) \cdot D\phi(x, t) + \text{tr}(A(\xi) D^2 \phi(x, t)) \} d\xi \\ &\leq |u(x, t) - v(x, t)| \text{ess sup}_{m \leq \xi \leq M} \{ F'(\xi) \cdot D\phi(x, t) + \text{tr}(A(\xi) D^2 \phi(x, t)) \}. \end{aligned}$$

How are HJB and CDE connected?

For a.e. $x \in \mathbb{R}^N$ and $t \geq 0$:

$$I := \sum_{i=1}^d q_i(u, v) \partial_{x_i} \phi + \sum_{i,j=1}^d r_{ij}(u, v) \partial_{x_i x_j}^2 \phi = q(u, v) \cdot D\phi + \text{tr}(r(u, v) D^2 \phi)$$

$$\begin{aligned} I &= \text{sign}(u(x, t) - v(x, t)) \times \\ &\quad \times \int_{v(x, t)}^{u(x, t)} \{ F'(\xi) \cdot D\phi(x, t) + \text{tr}(A(\xi) D^2 \phi(x, t)) \} d\xi \\ &\leq |u(x, t) - v(x, t)| \text{ess sup}_{m \leq \xi \leq M} \{ F'(\xi) \cdot D\phi(x, t) + \text{tr}(A(\xi) D^2 \phi(x, t)) \}. \end{aligned}$$

How are HJB and CDE connected?

Going back to (KI), we get

$$\begin{aligned} \int_{\mathbb{R}^d} |u - v|(x, T) \phi(x, T) dx &\leq \int_{\mathbb{R}^d} |u_0 - v_0|(x) \phi(x, 0) dx \\ + \iint_{\mathbb{R}^d \times (0, T)} |u - v| &\times \\ &\times \left(\partial_t \phi + \operatorname{ess\,sup}_{m \leq \xi \leq M} \{ F'(\xi) \cdot D\phi(x, t) + \operatorname{tr}(A(\xi) D^2 \phi(x, t)) \} \right) dx dt. \end{aligned}$$

We recognize the backward version of the PDE in (HJB) with $\mathcal{E} = [m, M]$, $b = F'$, and $a = A$.

By approximation, we can take $\phi(x, t) = \psi(x, T - t)$ in the above.

BUT if u_0, v_0 are only bounded, then ψ needs to be integrable.

The Cauchy problems

We consider the following Cauchy problem in $\mathbb{R}^N \times (0, \infty)$:

$$(HJB) \quad \begin{cases} \partial_t \psi = \sup_{\xi \in \mathcal{E}} \{ b(\xi) \cdot D\psi + \text{tr}(a(\xi) D^2 \psi) \}, \\ \psi(\cdot, 0) = \psi_0, \end{cases}$$

where $\psi_0 \in C_b(\mathbb{R}^N) \cap "L^1(\mathbb{R}^N)"$ and

$$(H1) \quad \begin{cases} \mathcal{E} \text{ is a nonempty set,} \\ b : \mathcal{E} \rightarrow \mathbb{R}^d \text{ bounded function,} \\ a = \sigma^a (\sigma^a)^T \text{ for some bounded } \sigma^a : \mathcal{E} \rightarrow \mathbb{R}^{d \times K}, \end{cases}$$

with K being a fixed integer.

The problem is often given as

$$\partial_t \psi = H(D\psi, D^2\psi) \quad \text{with} \quad H(p, X) = \sup_{\xi \in \mathcal{E}} \{b(\xi) \cdot p + \text{tr}(a(\xi)X)\}.$$

- It is a fully nonlinear equation in nondivergence form.
- The vector b and the matrix a may degenerate.
- Classical solutions may not exist, and a.e.-solutions may be nonunique.

- The works of Crandall, Lions, Evans, Ishii, Jensen,... suggest that viscosity solutions are indeed the right solution concept: existence, uniqueness and stability in C_b .
- Viscosity solutions are pointwise solutions, and the test function test the equation at local extremal points.

We also consider the following Cauchy problem in $\mathbb{R}^N \times (0, \infty)$:

$$(CDE) \quad \begin{cases} \partial_t u + \operatorname{div} F(u) = \operatorname{div} (A(u) Du), \\ u(\cdot, 0) = u_0, \end{cases}$$

where $u_0 \in L^\infty(\mathbb{R}^N)$ and

$$(H2) \quad \begin{cases} F \in W_{\text{loc}}^{1,\infty}(\mathbb{R}, \mathbb{R}^d), \\ A = \sigma^A (\sigma^A)^T \text{ with } \sigma^A \in L_{\text{loc}}^\infty(\mathbb{R}, \mathbb{R}^{d \times K}). \end{cases}$$

The problem was given as

$$\partial_t u + \operatorname{div} F(u) = \operatorname{div} (A(u) Du).$$

- It is an equation in divergence form.
- The vector F and the matrix A may degenerate, and we get a mixture of hyperbolic and parabolic equations. Moreover, the diffusion is anisotropic.
- Classical solutions may not exist, and distributional solutions may be nonunique.
- The works of Kružkov, Carrillo, Chen, Perthame,... suggest that entropy solutions are indeed the right solution concept: existence, uniqueness and stability in L^1 .
- Entropy solutions are “signed” distributional solutions.

Selective summary of previous results

Well-known that (HJB) is stable in C_b .



M. G. CRANDALL, H. ISHII, P.-L. LIONS. User's guide to viscosity solutions of second order partial differential equations. *Bull. Amer. Math. Soc. (N.S.)*, 27(1):1–67, 1992.



M. BARDI, I. CAPUZZO-DOLCETTA. *Optimal control and viscosity solutions of Hamilton-Jacobi-Bellman equations*. Systems & Control: Foundations & Applications. Birkhäuser Boston, Inc., Boston, MA, 1997.

Well-known that (CDE) is stable in L^1 .



J. CARRILLO. Entropy solutions for nonlinear degenerate problems. *Arch. Ration. Mech. Anal.*, 147(4):269–361, 1999.



G.-Q. CHEN, B. PERTHAME. Well-posedness for non-isotropic degenerate parabolic-hyperbolic equations. *Ann. Inst. H. Poincaré Anal. Non Linéaire*, 20(4):645–668, 2003.



M. BENDAHMANE, K. H. KARLSEN. Renormalized entropy solutions for quasi-linear anisotropic degenerate parabolic equations. *SIAM J. Math. Anal.*, 36(2):405–422, 2004.

Note that L^1 -like stability (even well-posedness) for (HJB) is unusual, and that stability of $\|\cdot\|_{L^\infty}$ is not true for (CDE).

Previously known L^∞ -stability for (CDE)

When $A(u) \equiv 0$ in (CDE), we have the classical result

$$\begin{aligned} & \int_{\mathbb{R}^N} |u(x, t) - v(x, t)| \mathbf{1}_{B(x_0, R)}(x) \, dx \\ & \leq \int_{\mathbb{R}^N} |u_0(x) - v_0(x)| \mathbf{1}_{B(x_0, R+L_F t)}(x) \, dx. \end{aligned}$$

Note that $\mathbf{1}_{B(x_0, R+L_F t)}$ is a “supersolution” of

$$\begin{cases} \partial_t \psi = L_F |D\psi|, \\ \psi(\cdot, 0) = \mathbf{1}_{B(x_0, R)}. \end{cases}$$



S. N. KRUŽKOV. First order quasilinear equations with several independent variables. *Mat. Sb. (N.S.)*, 81(123):228–255, 1970.

Finally, finite speed of propagation is encoded in the estimate.

Previously known L^∞ -stability for (CDE)

When $A(u) \equiv 1$ in (CDE) and K is the heat kernel, we have

$$\begin{aligned} & \int_{\mathbb{R}^N} |u(x, t) - v(x, t)| \mathbf{1}_{B(x_0, R)} dx \\ & \leq \int_{\mathbb{R}^N} |u_0(x) - v_0(x)| K(\cdot, t) *_x \mathbf{1}_{B(x_0, R+L_F t)}(x) dx. \end{aligned}$$

Note that $K(\cdot, t) *_x \mathbf{1}_{B(x_0, R+L_F t)}(x)$ is a “supersolution” of

$$\begin{cases} \partial_t \psi = L_F |D\psi| + \Delta \psi, \\ \psi(\cdot, 0) = \mathbf{1}_{B(x_0, R)}. \end{cases}$$



N. ALIBAUD. Entropy formulation for fractal conservation laws. *J. Evol. Equ.*, 7(1):145–175, 2007.

Finally, note that we have finite infinite speed of propagation.

Previously known L^∞ -stability for (CDE)

When $A(u) = \varphi'(u)l$ in (CDE), we have

$$\begin{aligned} & \int_{\mathbb{R}^N} |u(x, t) - v(x, t)| \mathbf{1}_{B(x_0, R)} \, dx \\ & \leq \int_{\mathbb{R}^N} |u_0(x) - v_0(x)| \Phi(\cdot, L_\varphi t) *_x \mathbf{1}_{B(x_0, R+1+L_F t)}(x) \, dx. \end{aligned}$$

Note that $\Phi(\cdot, L_\varphi t) *_x \mathbf{1}_{B(x_0, R+1+L_F t)}(x)$ is a “supersolution” of

$$\begin{cases} \partial_t \psi = L_F |D\psi| + L_\varphi (\Delta \psi)^+, \\ \psi(x, 0) = \mathbf{1}_{B(x_0, R)}. \end{cases}$$



JE, E. R. JAKOBSEN. L^1 contraction for bounded (nonintegrable) solutions of degenerate parabolic equations. *SIAM J. Math. Anal.*, 46(6):3957–3982, 2014.

Again, we note the finite infinite speed of propagation.

Previously known L^∞ -stability for (CDE)

When $A(u)$ “general” in (CDE), we have

$$\begin{aligned} & \int_{\mathbb{R}^N} |u(x, t) - v(x, t)| e^{-|x|} dx \\ & \leq e^{(L_F + L_A)t} \int_{\mathbb{R}^N} |u_0(x) - v_0(x)| e^{-|x|} dx. \end{aligned}$$

Note that $e^{(L_F + L_A)t} e^{-|x|}$ is a “supersolution” of

$$\begin{cases} \partial_t \psi = L_F |D\psi| + L_A (\sup_{|h|=1} D^2 \psi h \cdot h)^+, \\ \psi(x, 0) = e^{-|x|}. \end{cases}$$



G.-Q. CHEN, E. DiBENEDETTO. Stability of entropy solutions to the Cauchy problem for a class of nonlinear hyperbolic-parabolic equations. *SIAM J. Math. Anal.*, 33(4):751–762, 2001.



H. FRID. Decay of Almost Periodic Solutions of Anisotropic Degenerate Parabolic-Hyperbolic Equations. In *Non-linear partial differential equations, mathematical physics, and stochastic analysis*, EMS Ser. Congr. Rep., pages 183–205. Eur. Math. Soc., Zürich, 2018.

A natural question appears:

Can we obtain

$$\|\psi(\cdot, t) - \hat{\psi}(\cdot, t)\|_{L^1} \leq \|\psi_0 - \hat{\psi}_0\|_{L^1}$$

where $\psi, \hat{\psi}$ solve (HJB) with initial data $\psi_0, \hat{\psi}_0$?

Not really studied, and only some results for (HJ).



C.-T. LIN, E. TADMOR. L^1 -stability and error estimates for approximate Hamilton-Jacobi solutions. *Numer. Math.*, 87(4):701–735, 2001.

What is possible? Initial guess

Consider the eikonal equation

$$\begin{cases} \partial_t \psi = C(|\partial_{x_1} \psi| + |\partial_{x_2} \psi| + \cdots + |\partial_{x_N} \psi|), \\ \psi(\cdot, 0) = \psi_0. \end{cases}$$

Control theory gives the following representation formula:

$$\psi(x, t) = \sup_{x+Ct[-1,1]^N} \psi_0 = \sup_{\bar{Q}_{Ct}(x)} \psi_0.$$

Moreover,

$$\int_{\mathbb{R}^N} \sup_{\bar{Q}_r(x)} \psi(\cdot, t) dx = \int_{\mathbb{R}^N} \sup_{\bar{Q}_{r+Ct}(x)} \psi_0(x) dx \leq \tilde{C}(t) \int_{\mathbb{R}^N} \sup_{\bar{Q}_r(x)} \psi_0 dx.$$

We consider the normed space

$$L_{\text{int}}^\infty(\mathbb{R}^N) := \{\psi \in L^1(\mathbb{R}^N) \cap L^\infty(\mathbb{R}^N) : \|\psi\|_{L_{\text{int}}^\infty(\mathbb{R}^N)} < \infty\}$$

where

$$\|\psi\|_{L_{\text{int}}^\infty(\mathbb{R}^N)} := \int_{\mathbb{R}^N} \text{ess sup}_{\overline{Q_1(x)}} |\psi| dx.$$

Theorem

- L_{int}^∞ is a Banach space.
- The space L_{int}^∞ is continuously embedded into $L^1 \cap L^\infty$.
- $\int_{\mathbb{R}^N} \text{ess sup}_{\overline{Q_{r+\varepsilon}(x)}} |\psi| dx \leq C_{r,\varepsilon} \int_{\mathbb{R}^N} \text{ess sup}_{\overline{Q_r(x)}} |\psi| dx.$

The same for second order equations?

Consider

$$\begin{cases} \partial_t \psi = (\partial_{xx}^2 \psi)^+, \\ \psi(\cdot, 0) = \psi_0. \end{cases}$$

For nonnegative solutions, we are able to obtain

$$\psi(\cdot, t) \in L^1 \quad \iff \quad \psi_0 \in L_{\text{int}}^\infty.$$

It seems that L_{int}^∞ is a good space for (HJB).

Largest subspace of L^1 stable by the equation (HJB)

Consider a space E such that

$$\begin{cases} E \text{ is a vector subspace of } C_b \cap L^1, \\ E \text{ is a normed space,} \\ E \text{ is continuously embedded into } L^1, \end{cases}$$

and the C_b -semigroup $G(t)$ associated with (HJB) such that

$G(t)$ maps E into itself and $G(t) : E \rightarrow E$ is continuous.

Theorem (Best possible E , [Alibaud & JE & Jakobsen, 2018])

The space $C_b \cap L_{\text{int}}^\infty$ satisfies the above properties. Moreover, any other E satisfying the above properties is continuously embedded into $C_b \cap L_{\text{int}}^\infty$.

Theorem (L_{int}^{∞} -stability, [Alibaud & JE & Jakobsen, 2018])

Assume (H1). There exists a modulus of continuity ω_N such that, for viscosity solutions $\psi, \hat{\psi}$ of (HJB) with respective initial data $\psi_0, \hat{\psi}_0 \in C_b \cap L_{\text{int}}^{\infty}$, we have

$$\|\psi - \hat{\psi}\|_{L_{\text{int}}^{\infty}} \leq (1 + t|H|_{\text{conv}})^N (1 + \omega_N(t|H|_{\text{diff}})) \|\psi_0 - \hat{\psi}_0\|_{L_{\text{int}}^{\infty}}.$$

- The modulus of continuity $\omega_N(r)$ will typically be like \sqrt{r} .
- The seminorms $|H|_{\text{conv}}, |H|_{\text{diff}}$ measure nonlinearities in (HJB).

As we saw, we only had a quasicontraction when the diffusion was linear and a contraction when the whole equation was linear.

Theorem (L_{int}^{∞} -quasicontraction, [Alibaud & JE & Jakobsen, 2018])

Assume (H1). For viscosity solutions $\psi, \hat{\psi}$ of (HJB) with respective initial data $\psi_0, \hat{\psi}_0 \in C_b \cap L_{\text{int}}^{\infty}$, we have

$$\| \! \| \! \| \psi - \hat{\psi} \| \! \| \! \| \leq e^{t \max\{|H|_{\text{conv}}, |H|_{\text{diff}}\}} \| \! \| \! \| \psi_0 - \hat{\psi}_0 \| \! \| \! \|.$$

- $\| \! \| \! \| \cdot \| \! \| \! \|$ is equivalent to $\| \cdot \|_{L_{\text{int}}^{\infty}}$.
- Remarkably, $\| \! \| \! \| \cdot \| \! \| \! \|$ does not depend on the semigroup $\psi_0 \xrightarrow{t} \psi$, but rather a fixed semigroup of some model equation.

L^∞ -stability for (CDE)

Let $\mathcal{E} = [m, M]$, $b = F'$, and $a = A$ in (HJB).

Theorem (L^∞ -stability, [Alibaud & JE & Jakobsen, 2018])

Assume (H2), u_0, v_0 take values in $[m, M]$, and $0 \leq \psi_0 \in BLSC$. Then the associated entropy solutions u, v of (CDE) and viscosity (minimal) solution ψ of (HJB) satisfy, for all $t \geq 0$,

$$\int_{\mathbb{R}^N} |u(x, t) - v(x, t)| \psi_0(x) dx \leq \int_{\mathbb{R}^N} |u_0(x) - v_0(x)| \psi(x, t) dx.$$

- Any other viscosity solution $\hat{\psi}$ of (HJB) will satisfy $\psi \leq \hat{\psi}$. Hence, it includes ALL previous results of this type.
- To make the right-hand side finite, we could require $u_0 - v_0 \in L^1$ or $\psi_0 \in L_{\text{int}}^\infty$.
- When we drop C_b , we might have nonunique solutions, and therefore we consider minimal solutions (unique by definition).

Recall that we already proved this using the Kato inequality (KI):

$$\begin{aligned} \int_{\mathbb{R}^d} |u - v|(x, T) \phi(x, T) \, dx &\leq \int_{\mathbb{R}^d} |u_0 - v_0|(x) \phi(x, 0) \, dx \\ + \iint_{\mathbb{R}^d \times (0, T)} |u - v| &\times \\ &\times \left(\partial_t \phi + \operatorname{ess\,sup}_{m \leq \xi \leq M} \{ F'(\xi) \cdot D\phi(x, t) + \operatorname{tr}(A(\xi) D^2 \phi(x, t)) \} \right) \, dx \, dt. \end{aligned}$$

By approximation, we can take $\phi(x, t) = \psi(x, T - t)$ in the above.

A duality result

For the respective unique solutions u, ψ of (CDE),(HJB) define

$$S(t) : u_0 \in L^\infty(\mathbb{R}^d) \mapsto u(\cdot, t) \in L^\infty(\mathbb{R}^d) \quad \forall t \geq 0,$$

$$G_{m,M}(t) : \psi_0 \in C_b \cap L_{\text{int}}^\infty(\mathbb{R}^d) \mapsto \psi(\cdot, t) \in C_b \cap L_{\text{int}}^\infty(\mathbb{R}^d) \quad \forall t \geq 0.$$

Theorem (Semigroup duality [Alibaud & JE & Jakobsen, 2018])

Assume (H2), $m < M$, and consider the above semigroups. Then $\{G_{m,M}(t)\}_{t \geq 0}$ is the smallest strongly continuous semigroup on $C_b \cap L_{\text{int}}^\infty(\mathbb{R}^d)$ satisfying, for all $t \geq 0$,

$$\int_{\mathbb{R}^d} |S(t)u_0 - S(t)v_0| \psi_0 \, dx \leq \int_{\mathbb{R}^d} |u_0 - v_0| G_{m,M}(t) \psi_0 \, dx,$$

for every $u_0, v_0 \in L^\infty(\mathbb{R}^d, [m, M])$, every $0 \leq \psi_0 \in C_b \cap L_{\text{int}}^\infty(\mathbb{R}^d)$.

Given $S(t)$, then the above inequality characterizes $G_{m,M}(t)$.

A duality result, open problem

Theorem (Semigroup duality [Alibaud & JE & Jakobsen, 2018])

Assume (H2), $m < M$, and consider the above semigroups. Then $\{G_{m,M}(t)\}_{t \geq 0}$ is the smallest strongly continuous semigroup on $C_b \cap L_{\text{int}}^\infty(\mathbb{R}^d)$ satisfying, for all $t \geq 0$,

$$\int_{\mathbb{R}^d} |S(t)u_0 - S(t)v_0| \psi_0 \, dx \leq \int_{\mathbb{R}^d} |u_0 - v_0| G_{m,M}(t) \psi_0 \, dx,$$

for every $u_0, v_0 \in L^\infty(\mathbb{R}^d, [m, M])$, every $0 \leq \psi_0 \in C_b \cap L_{\text{int}}^\infty(\mathbb{R}^d)$.

The dual question:

Given $G_{m,M}(t)$. Then $S(t)$ is a weak- \star continuous semigroup on L^∞ satisfying the above inequality.

Is $S(t)$ the ONLY such semigroup satisfying such an inequality? If no, which ones do?

Note that

$$\sup_{\varepsilon} \{b \cdot D\psi + \operatorname{tr}(aD^2\psi)\} \leq C_b |D\psi| + C_a \left(\sup_{|h|=1} D^2\psi h \cdot h \right)^+$$

or

$$\partial_t \psi - \sup_{\varepsilon} \{b \cdot D\psi + \operatorname{tr}(aD^2\psi)\} \geq \partial_t \psi - C_b |D\psi| - C_a \left(\sup_{|h|=1} D^2\psi h \cdot h \right)^+$$

Let us therefore find an integrable supersolution of

$$\partial_t \psi = C_b |D\psi| + C_a \left(\sup_{|h|=1} D^2\psi h \cdot h \right)^+.$$

Note that

$$\sup_{\mathcal{E}} \{b \cdot D\psi + \operatorname{tr}(aD^2\psi)\} \leq C_b |D\psi| + C_a \left(\sup_{|h|=1} D^2\psi h \cdot h \right)^+$$

or

$$\partial_t \psi - \sup_{\mathcal{E}} \{b \cdot D\psi + \operatorname{tr}(aD^2\psi)\} \geq \partial_t \psi - C_b |D\psi| - C_a \left(\sup_{|h|=1} D^2\psi h \cdot h \right)^+$$

Let us therefore find an integrable supersolution of

$$\partial_t \psi = C_a \left(\sup_{|h|=1} D^2\psi h \cdot h \right)^+.$$

Recall that for $\operatorname{tr}(aD^2\psi) = a\Delta\psi$, $\sup_{|h|=1} D^2\psi h \cdot h = \Delta\psi$.

Lemma (Fundamental solution? [Alibaud & JE & Jakobsen, 2018])

Consider solutions ψ_n of

$$\begin{cases} \partial_t \psi_n = (\partial_{xx}^2 \psi_n)^+, \\ \psi_n(\cdot, 0) = n\omega(n\cdot) \approx \delta_0. \end{cases}$$

Then, for all $(x, t) \in \mathbb{R} \times (0, \infty)$,

$$\lim_{n \rightarrow \infty} \psi_n(x, t) = \infty.$$

Important ingredient in the proofs, L^1 -supersolution

$$\partial_t \psi = (\Delta \psi)^+ = \begin{cases} \Delta \psi, & \Delta \psi > 0 \\ 0, & \Delta \psi \leq 0 \end{cases}$$

So, we want to keep the “convex” regions of the heat equation.



We thus search for a profile of the heat equation with second derivative positive.

Define

$$U(r) := c_0 \int_r^\infty e^{-\frac{s^2}{4}} ds.$$

Note that U satisfies

$$U(0) = 1, \quad \frac{r}{2}U' + U'' = 0, \quad U' < 0, \quad \text{and} \quad U'' > 0.$$

Moreover, when $N = 1$, $(x, t) \mapsto U(|x|/\sqrt{t})$ solves

$$\partial_t U = \partial_{xx}^2 U = (\partial_{xx}^2 U)^+ \quad \text{on} \quad \mathbb{R} \setminus \{0\} \times (0, \infty).$$

Let us now check that

$$(x, t) \mapsto U((|x| - 1)^+ / \sqrt{t})$$

is a viscosity supersolution of

$$\partial_t \psi = \left(\sup_{|h|=1} D^2 \psi h \cdot h \right)^+.$$

We note that we have 3 different regions to check:

1. $\{|x| < 1\}$
2. $\{|x| > 1\}$
3. $\{|x| = 1\}$

Important ingredient in the proofs, L^1 -supersolution

• **The region** $\{|x| < 1\}$. Here $U((|x| - 1)^+/\sqrt{t}) = U(0) = 1$ for all $t > 0$. And it thus satisfies the equation.

• **The region** $\{|x| > 1\}$. Here $U((|x| - 1)^+/\sqrt{t}) = U((|x| - 1)/\sqrt{t})$. Let us check that it satisfies the equation pointwise:

$$\partial_t U((|x| - 1)/\sqrt{t}) = -\frac{1}{t} \frac{r}{2} U'(r)$$

and

$$\begin{aligned} & \sum_{i,j} \partial_{x_i x_j}^2 U((|x| - 1)/\sqrt{t}) h_i h_j \\ &= (N|x|^2|h|^2 - (x \cdot h)^2) \frac{U'}{|x|^3 \sqrt{t}} + (x \cdot h)^2 \frac{U''}{|x|^2 t} \end{aligned}$$

Important ingredient in the proofs, L^1 -supersolution

• **The region** $\{|x| < 1\}$. Here $U((|x| - 1)^+/\sqrt{t}) = U(0) = 1$ for all $t > 0$. And it thus satisfies the equation.

• **The region** $\{|x| > 1\}$. Here $U((|x| - 1)^+/\sqrt{t}) = U((|x| - 1)/\sqrt{t})$. Let us check that it satisfies the equation pointwise:

$$\partial_t U((|x| - 1)/\sqrt{t}) = -\frac{1}{t} \frac{r}{2} U'(r)$$

and

$$\begin{aligned} & \sup_{|h|=1} \sum_{i,j} \partial_{x_i x_j}^2 U((|x| - 1)/\sqrt{t}) h_i h_j \\ &= (N|x|^2 - |x|^2) \frac{U'}{|x|^3 \sqrt{t}} + |x|^2 \frac{U''}{|x|^2 t} \\ &\leq \frac{U''}{t} \end{aligned}$$

• **The region** $\{|x| < 1\}$. Here $U((|x| - 1)^+/\sqrt{t}) = U(0) = 1$ for all $t > 0$. And it thus satisfies the equation.

• **The region** $\{|x| > 1\}$. Here $U((|x| - 1)^+/\sqrt{t}) = U((|x| - 1)/\sqrt{t})$. Let us check that it satisfies the equation pointwise:

$$\partial_t U(r) - \left(\sup_{|h|=1} D^2 U(r) h \cdot h \right)^+ \geq -\frac{1}{t} \left(\frac{r}{2} U'(r) + U''(r) \right) = 0.$$

• **The region** $\{|x| = 1\}$. We need to check the subset. But it is empty.

Important ingredient in the proofs, L^1 -supersolution

Let us now check that

$$(x, t) \mapsto U((|x| - 1)^+ / \sqrt{t}) \quad \text{with} \quad U(r) = c_0 \int_r^\infty e^{-\frac{s^2}{4}} ds.$$

is integrable:

$$\begin{aligned} & \int U((|x| - 1)^+ / \sqrt{t}) dx \\ &= \int_{|x| \leq 1} U(0) dx + \int_{|x| > 1} U((|x| - 1) / \sqrt{t}) dx \\ &\sim 1 + \int_0^\infty r^{d-1} \int_r^\infty e^{-\frac{s^2}{4}} ds dr \\ &\sim 1 + \int_0^\infty s^d e^{-\frac{s^2}{4}} ds < \infty. \end{aligned}$$

Thank you for your attention!

